

The 3rd quiz in Pattern Recognition and Machine Learning

(Answer)

Ex. 4.1

4.1 Solutions

4.1.1 Uncorrelated does not imply independent

We have

$$E[X] = 0 \quad (4.1)$$

$$\text{var}[X] = (1 - -1)^2/12 = 1/3 \quad (4.2)$$

$$E[Y] = E[X^2] = \text{var}[X] + (E[X])^2 = 1/3 + 0 \quad (4.3)$$

$$E[XY] = \int p(x)x^3 dx = \frac{1}{2} \left[-\left(\int_{-1}^0 x^3 dx\right) + \left(\int_0^1 x^3 dx\right) \right] \quad (4.4)$$

$$= \frac{1}{2} \left[\frac{-1}{4} [x^4]_{-1}^0 + \frac{1}{4} [x^4]_0^1 \right] = \frac{1}{8} [-1 + 1] = 0 \quad (4.5)$$

where we have split the integral into two pieces, since x^3 changes sign in the interval $[-1, 1]$. Hence

$$\rho = \frac{\text{cov}[X, Y]}{\sigma_X \sigma_Y} = \frac{E[XY] - E[X]E[Y]}{\sigma_X \sigma_Y} = \frac{0}{\sigma_X \sigma_Y} = 0 \quad (4.6)$$

4.1.5 Normalization constant for a multidimensional Gaussian

Ex. 4.1

Let $\Sigma = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^T$, so

$$\Sigma^{-1} = \mathbf{U}^{-T}\mathbf{\Lambda}^{-1}\mathbf{U}^{-1} = \mathbf{U}\mathbf{\Lambda}^{-1}\mathbf{U} = \sum_{i=1}^p \frac{1}{\lambda_i} \mathbf{u}_i \mathbf{u}_i^T \quad (4.30)$$

Hence

$$(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}) = (\mathbf{x} - \boldsymbol{\mu})^T \left(\sum_{i=1}^p \frac{1}{\lambda_i} \mathbf{u}_i \mathbf{u}_i^T \right) (\mathbf{x} - \boldsymbol{\mu}) \quad (4.31)$$

$$= \sum_{i=1}^p \frac{1}{\lambda_i} (\mathbf{x} - \boldsymbol{\mu})^T \mathbf{u}_i \mathbf{u}_i^T (\mathbf{x} - \boldsymbol{\mu}) = \sum_{i=1}^p \frac{y_i^2}{\lambda_i} \quad (4.32)$$

where $y_i \triangleq \mathbf{u}_i^T (\mathbf{x} - \boldsymbol{\mu})$. The \mathbf{y} variables define a new coordinate system that is shifted (by $\boldsymbol{\mu}$) and rotated (by \mathbf{U}) with respect to the original x coordinates: $\mathbf{y} = \mathbf{U}(\mathbf{x} - \boldsymbol{\mu})$. Hence $\mathbf{x} = \mathbf{U}^T \mathbf{y} + \boldsymbol{\mu}$.

The Jacobian of this transformation, from \mathbf{y} to \mathbf{x} , is a matrix with elements

$$J_{ij} = \frac{\partial x_i}{\partial y_j} = U_{ji} \quad (4.33)$$

so $\mathbf{J} = \mathbf{U}^T$ and $|\mathbf{J}| = 1$.

So

$$\int \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu})\right) d\mathbf{x} = \int \prod_i \exp\left(-\frac{1}{2} \sum_i \frac{y_i^2}{\lambda_i}\right) dy_i |\mathbf{J}| \quad (4.34)$$

$$= \prod_i \sqrt{2\pi\lambda_i} = |2\pi\Sigma| \quad (4.35)$$

Ex. 4.17

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4.1.7 Conditioning a bivariate Gaussian

1. We have that $P(X_2|x_1) = \mathcal{N}(X_2|\mu_{2|1}, \Sigma_{2|1})$, where

$$\mu_{2|1} = \mu_2 + \frac{\sigma_{12}}{\sigma_1^2} (x_1 - \mu_1) = \mu_2 + \frac{\sigma_2 \rho}{\sigma_1} (x_1 - \mu_1)$$

$$\sigma_{2|1}^2 = \sigma_2^2 - \frac{\sigma_{12}^2}{\sigma_1^2} = \sigma_2^2 (1 - \rho^2)$$

2. Now $\sigma_{12} = \rho$, so the above becomes

$$\mu_{2|1} = \mu_2 + \rho(x_1 - \mu_1)$$

$$\sigma_{2|1}^2 = 1 - \rho^2$$

Ex. 4.1.1

4.1.11 Derivation of the NIW posterior

Multiplying prior and likelihood we get

$$p(\boldsymbol{\mu}, \boldsymbol{\Sigma} | \mathcal{D}) \propto |\boldsymbol{\Sigma}|^{-\frac{\nu_0 + D + 2 + N}{2}} \text{etr} \left[-\frac{1}{2} \boldsymbol{\Sigma}^{-1} (\mathbf{S}_{\bar{x}} + \mathbf{S}_0 + \right. \quad (4.65)$$

$$\left. + N(\boldsymbol{\mu} - \bar{\mathbf{x}})(\boldsymbol{\mu} - \bar{\mathbf{x}})^T + \kappa_0(\boldsymbol{\mu} - \mathbf{m}_0)(\boldsymbol{\mu} - \mathbf{m}_0)^T) \right] \quad (4.66)$$

where $\text{etr}(\mathbf{M}) = \exp(\text{tr}(\mathbf{M}))$. Using the hint this becomes

$$p(\boldsymbol{\mu}, \boldsymbol{\Sigma} | \mathcal{D}) \propto |\boldsymbol{\Sigma}|^{-\frac{\nu_N + D + 2}{2}} \text{etr} \left[-\frac{1}{2} \boldsymbol{\Sigma}^{-1} \left(\mathbf{S}_{\bar{x}} + \mathbf{S}_0 + \frac{\kappa_0 N}{\kappa_N} (\bar{\mathbf{x}} - \mathbf{m}_0)(\bar{\mathbf{x}} - \mathbf{m}_0)^T \right) \right] \quad (4.67)$$

$$\times \exp \left[-\frac{\kappa_N}{2} (\boldsymbol{\mu} - \mathbf{m}_N)^T \boldsymbol{\Sigma}^{-1} (\boldsymbol{\mu} - \mathbf{m}_N) \right] \quad (4.68)$$

For the NWI case,

$$p(\boldsymbol{\mu}, \boldsymbol{\Lambda} | \mathcal{D}) = \text{NWI}(\boldsymbol{\mu}, \boldsymbol{\Lambda} | \mathbf{m}_n, \kappa_n, \nu_n, \mathbf{W}_n) \quad (4.69)$$

$$\mathbf{m}_n = \frac{\kappa_0 \mathbf{m}_0 + N \bar{\mathbf{x}}}{\kappa_n} \quad (4.70)$$

$$\kappa_n = \kappa_0 + N \quad (4.71)$$

$$\nu_n = \nu_0 + N \quad (4.72)$$

$$\mathbf{W}_n^{-1} = \mathbf{W}_0^{-1} + \mathbf{S}_{\bar{x}} + \frac{\kappa_0 N}{\kappa_0 + N} (\bar{\mathbf{x}} - \mathbf{m}_0)(\bar{\mathbf{x}} - \mathbf{m}_0)^T \quad (4.73)$$